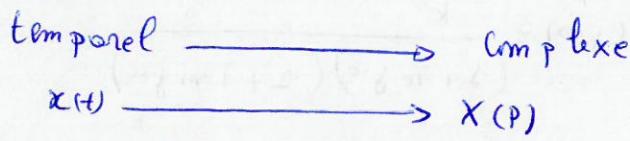


Asservissement : la transformée de Laplace

* Définit

le passage de :



$$X(P) = L(x(t)) = \int_0^{+\infty} x(t) \cdot e^{-Pt} dt$$

* Propriétés

- Dérivée : $\mathcal{R}(t) = \frac{d\theta(t)}{dt} \Rightarrow \mathcal{R}(P) = P \cdot \theta(P)$

- Intégrer : $\theta(t) = \int \mathcal{R}(t) dt \Rightarrow \theta(P) = \frac{1}{P} \mathcal{R}(P)$

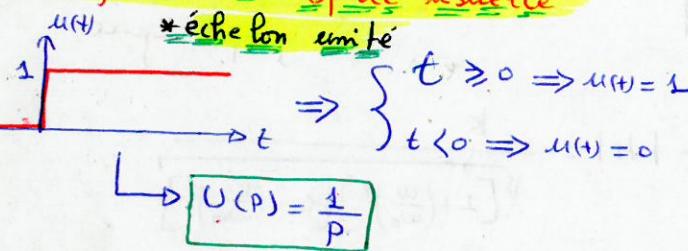
- théorème de la valeur finale

$$\lim_{t \rightarrow +\infty} x(t) \Rightarrow \lim_{P \rightarrow 0} P \cdot X(P)$$

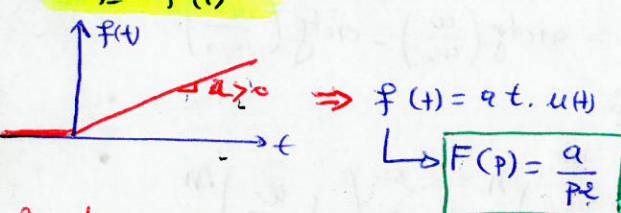
- théorème de la valeur initiale

$$\lim_{t \rightarrow 0} x(t) \Rightarrow \lim_{P \rightarrow +\infty} P \cdot X(P)$$

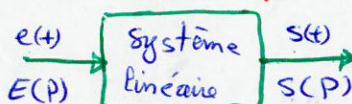
* Transformée de Laplace usuelle



* Temps : f(t)



* fmct im de transfert



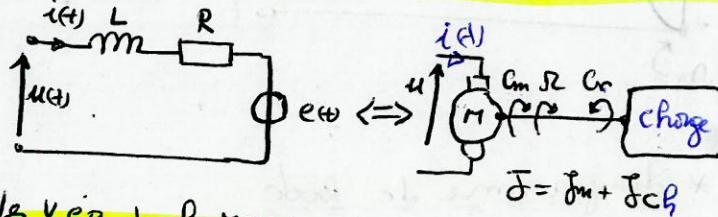
un système est linéaire si il est représenté par une équation différentielle :

$$b_0 s(t) + b_1 \frac{ds(t)}{dt} + \dots + b_m \frac{d^m s(t)}{dt^m} = a_0 e(t) + a_1 \frac{de(t)}{dt} + \dots + a_n \frac{d^n e(t)}{dt^n}$$

$$\Rightarrow H(P) = \frac{a_0 + a_1 P + \dots + a_n P^n}{b_0 + b_1 P + \dots + b_m P^m}$$

fmct de transfert

Application : machine à courant continu



les Vég de la RCC :

$$u(t) = L \frac{di(t)}{dt} + R i(t) + e(t) \Rightarrow E(t) = k SR(t)$$

$$\bar{I} \frac{d\bar{I}}{dt} = C_m(t) - C_r(t) - f \bar{I}(t) \Rightarrow I_m(t) = k i(t)$$

* la transformée de Laplace

$$U(P) = L \cdot P \cdot I(P) + R I(P) + E(P) \Rightarrow E(P) = k SR(P)$$

$$J \cdot P \cdot \mathcal{R}(P) = C_m(P) - C_r(P) - f \mathcal{R}(P) \Rightarrow C_m(P) = k I(P)$$

* fmct de transfert si $C_r = 0$

on : $\Rightarrow H(P) = \frac{\mathcal{R}(P)}{U(P)}$

$$\bar{J} P \mathcal{R}(P) + f \mathcal{R}(P) = C_m(P) = k I(P)$$

$$\Leftrightarrow \mathcal{R}(P) [\bar{J} P + f] = k I(P) \quad (1)$$

et que : $I(P)(L \cdot P + R) = U(P) - E(P)$

$$\Leftrightarrow I(P) = \frac{U(P)}{L \cdot P + R} - \frac{E(P)}{L \cdot P + R}$$

$$\Leftrightarrow I(P) = \frac{U(P)}{L \cdot P + R} - \frac{k \mathcal{R}(P)}{L \cdot P + R} \quad (2)$$

$$\Rightarrow \mathcal{R}(P) [\bar{J} \cdot P + f + \frac{k^2}{L \cdot P + R}] = \frac{U(P) k}{L \cdot P + R}$$

finalement :

$$H(P) = \frac{k}{k^2 + Rf + (R\bar{J} + Lf)P + L\bar{J}P^2}$$

on cherche la sortie $S(P)$ si $H(t)$ est en échelon

$$H(P) = \frac{S(P)}{U(P)} \Rightarrow U(P) = \frac{U_0}{P}$$

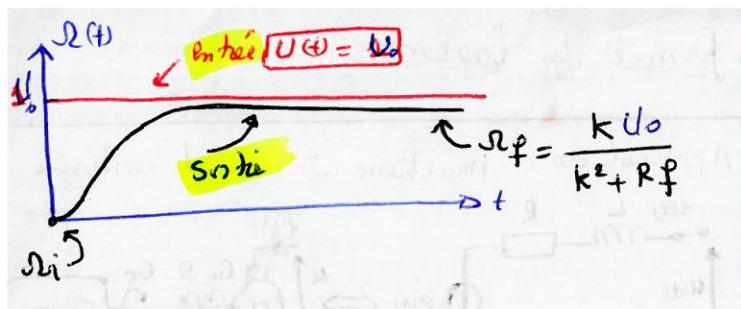
$$\Rightarrow \mathcal{R}(P) = \frac{U_0}{P} \times \frac{k}{k^2 + Rf + (R\bar{J} + Lf)P + L\bar{J}P^2}$$

* la valeur finale

$$\mathcal{R}_f = \lim_{P \rightarrow 0} P \cdot \mathcal{R}(P) \Rightarrow \mathcal{R}_f = \frac{k \cdot U_0}{k^2 + Rf}$$

* la valeur initiale

$$\mathcal{R}_i = \lim_{P \rightarrow +\infty} P \cdot \mathcal{R}(P) \Rightarrow \mathcal{R}_i = 0$$



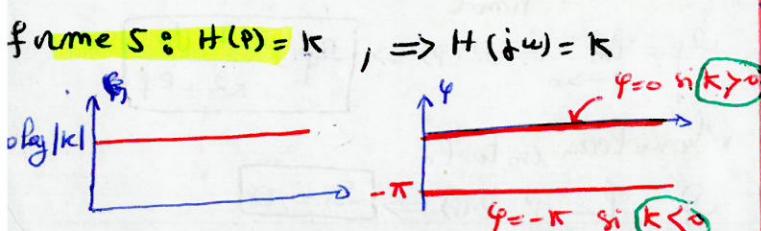
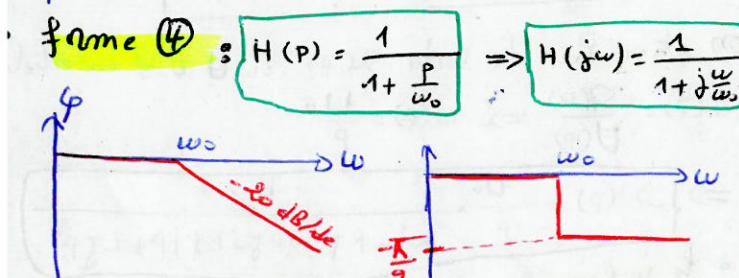
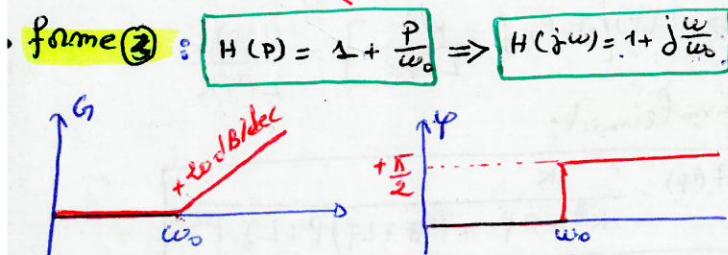
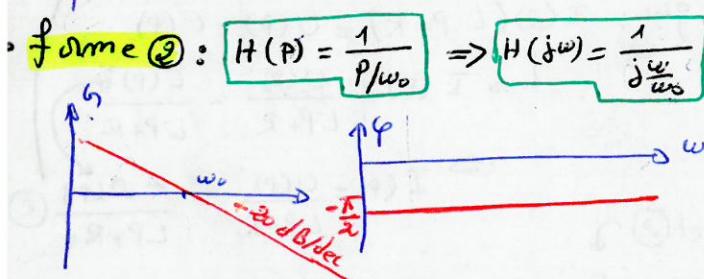
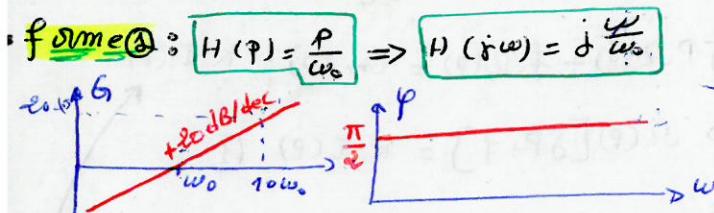
* Diagramme de Bode

$$H(P) \xrightarrow{P \rightarrow j\omega} H(j\omega)$$

il s'agit de la représentation de

$$\left\{ \begin{array}{l} G(j\omega) = 20 \log_{10}(|H(j\omega)|) \\ \varphi(j\omega) = \arg(H(j\omega)) \end{array} \right.$$

Pour tracer le diagramme de Bode on se servira de :

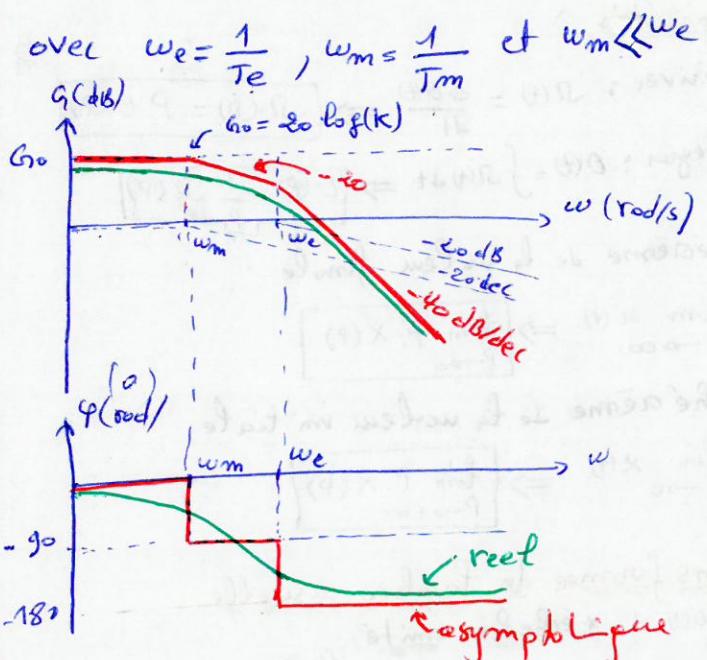


Ex: machine à courant continu

$$H(P) = \frac{K}{(1+T_e P)(1+T_m P)} \text{ avec } K > 0$$

$$\Rightarrow H(j\omega) = \frac{K}{(1+T_e j\omega)(1+T_m j\omega)}$$

$$= \frac{K}{(1+j\frac{\omega}{\omega_e})(1+j\frac{\omega}{\omega_m})}$$



$$\left\{ \begin{array}{l} |H| = \frac{K}{\sqrt{[1+(\frac{\omega}{\omega_e})^2][1+(\frac{\omega}{\omega_m})^2]}} \\ \varphi = -\arctg(\frac{\omega}{\omega_e}) - \arctg(\frac{\omega}{\omega_m}) \end{array} \right.$$

Rappel :

$$\left(1 + j \frac{\omega}{\omega_n}\right)^n \text{ ou } \left(j \frac{\omega}{\omega_n}\right)^n$$

$$\text{Pente} = m \times 20$$

$$\varphi = m \times \frac{\pi}{2}$$

$$\operatorname{arg}\left(\frac{a}{b}\right) = \operatorname{arg}(a) - \operatorname{arg}(b)$$

$$\operatorname{arg}(a \times b) = \operatorname{arg}(a) + \operatorname{arg}(b)$$

$$\operatorname{arctg}(a) + \operatorname{arctg}(b) = \operatorname{arctg}\left(\frac{a+b}{1-ab}\right)$$